

A Structure of FEM Matrix by Lagrange Basis Polynomials

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ABSTRACT

When the formula of Lagrange basis polynomials (LBP) and an algebraic identity of fractions are used in combination, a product of two different LBPs is re-expressed as a sum of two functions. When N is the number of basis polynomials for an element of FEM, the discretized matrix of an operator such as potential function may be dense and has $O(N^2)$ non-zero entries by its original definition, but it can be re-expressed in the combination of entries of reduced matrices which have only $O(N)$ values in total. Therefore, the amount of storage to represent the discretized operator would be reduced.

KEYWORDS

FEM, Matrix Element, Structure, Lagrange basis polynomials

1 INTRODUCTION

For modern high performance computer systems to solve problems of large sizes with low costs, it is important to reduce both amounts of storage requirement and storage transfer to overcome the bottleneck of the performance. Thus it would be important to make research on solution methods which reduce them.

We try a kind of position FEM (Axelsson and Baker, 2001)(Babuska et al., 1981) to solve

2 PDE PROBLEM BY FEM

In below, we consider a discretization of a simple PDE operator $(-\Delta + U(x))$ by FEM. Here $U(x)$ is a potential function depends only on the spatial coordinate x . For the simplicity, the region of the analysis is assumed rectangular whose sides are parallel to coordinate axes (Fig.1, Fig.2). We subdivide arbitrarily each edge of the region, and inside the FE made by the subdivision the unknown continuous function is approximated by a linear combination of LBPs. If the simulation

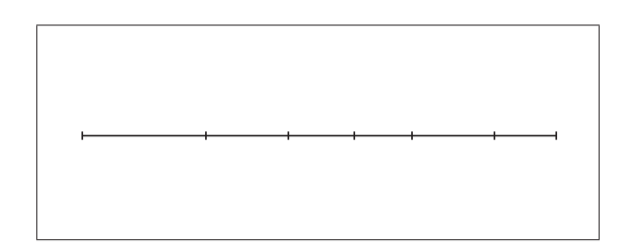


Figure 1: Conceptual FEM element subdivision(1-Dim)

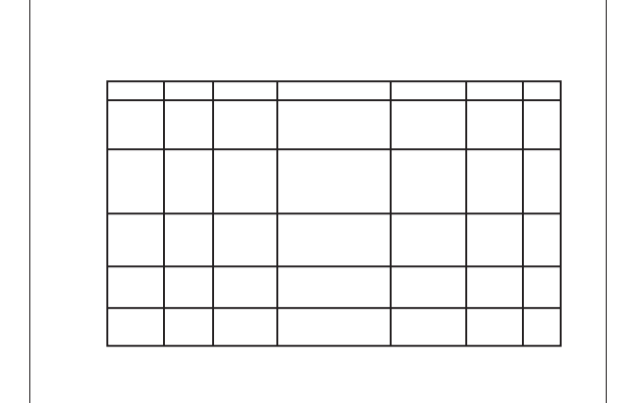


Figure 2: Conceptual FEM element subdivision(2-Dim)

nous linear equations of large size is solved by some iterative method whose coefficient matrix (global FEM matrix) is a collection of all small matrices (local matrices) discretized by FEM.

then matrix-vector multiplication of the global FEM matrix and the global vector is repeated many times.

3 STRUCTURE OF MATRIX ELEMENTS

The Lagrange interpolation formula inside an interval I at the n -distinct abscissas $(\alpha_j)_{j=1, \dots, n}$ gives the polynomial $f(x)$ which approximates a function $f(x)$ as:

$$\tilde{f}(x) = \sum_{j=1}^n \frac{P^{(j)}(x)}{(x - \alpha_j) P^{(j)}(\alpha_j)} f(\alpha_j).$$

Here, $P^{(j)}(x)$ is a degree n polynomial corresponds to the set of n abscissas:

$$P^{(j)}(x) = \prod_{k=1, k \neq j}^n (x - \alpha_k).$$

When the distribution of abscissas is selected well, the approximation of the original function f by the polynomial \tilde{f} would go better as the number of abscissas n increases.

To make the continuous connection of solution at the boundaries of adjacent local elements easily, the set of abscissas contains both ends of the interval I . (In this case, a distribution of abscissas with good property is the set of abscissas for Gauss-Lobatto quadrature formula, which is a closed quadrature formula. The abscissas of n points G-L quadrature formula over the standard interval $[-1, 1]$ are, both-ends of the interval ± 1 and $(n-2)$ zeros of the derivative of the Legendre polynomial of $(n-1)$ -th degree $L_{n-1}(x)$, all of which are inside the standard interval.) The LBPs for the function expansion are n different degree $(n-1)$ polynomials (Fig.3). n is called the order of basis of the expansion.

The basis functions of expansion are the LBPs, which are n different polynomials of degree $(n-1)$. To make the simple derivations of formulae, in the following the factors $1/P^{(j)}(\alpha_j)$ are removed from definitions of the LBPs. Thus the

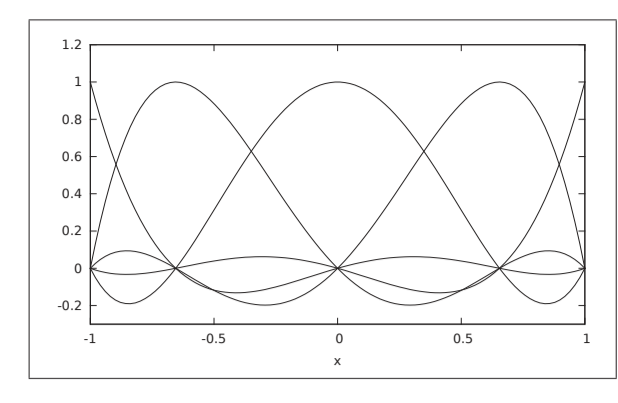


Figure 3: LBPs by 5-points G-L abscissas

basis polynomials are taken as:

$$v_k^{(j)}(x) = \frac{P^{(j)}(x)}{x - \alpha_k} \quad \text{for } k = 1, \dots, n.$$

If required, matrix elements based on the original LBPs can be obtained by scalings associated with the index k of the basis polynomials.

The essence of our method is as follows. By using an identity:

$$\frac{1}{x - \alpha} = \frac{1}{x - b} - \frac{1}{\alpha - b} \left(\frac{1}{x - \alpha} - \frac{1}{x - b} \right), \quad (\text{if } \alpha \neq b)$$

$\frac{P^{(j)}(x)}{x - \alpha_k} \times \frac{P^{(j)}(x)}{x - \alpha_l}$

$$= \frac{P^{(j)}(x)}{x - \alpha_l} \times \frac{P^{(j)}(x)}{x - \alpha_k} - \frac{1}{\alpha_l - \alpha_k} \left\{ \frac{P^{(j)}(x)}{x - \alpha_l} - \frac{P^{(j)}(x)}{x - \alpha_k} \right\}.$$

$= \frac{1}{\alpha_l - \alpha_k} (\Phi^{(j)}(x) - \Phi^{(j)}(x)).$

Here $\Phi^{(j)}(x) \equiv \{P^{(j)}(x)\}^2 / (x - \alpha_k)$, $k = 1, 2, \dots, n$ are n different polynomials of degree $2n - 1$.

3.1 Case of 1-Dimension

FEM Matrix of Potential

The local matrix of the potential $U(x)$ discretized by FEM using $v_k^{(j)}(x)$ for the basis functions is:

$$V_{ij} = \int_I v_i^{(j)}(x) U(x) v_j^{(j)}(x) dx = \int_I \frac{P^{(j)}(x)^2}{(x - \alpha_i)(x - \alpha_j)} U(x) dx.$$

If we define values:

$$L_k^{(j)} \equiv \int_I \frac{P^{(j)}(x)^2}{(x - \alpha_j)^2} U(x) dx, \quad \text{for } e = 0, 1,$$

then V_{ij} can be re-expressed as:

$$V_{ij} = \begin{cases} L_k^{(j)} & (i = j), \\ \frac{1}{\alpha_i - \alpha_j} (L_k^{(i)} - L_k^{(j)}), & (i \neq j). \end{cases}$$

Thus the symmetric matrix V_{ij} of discretization of the potential $U(x)$, has a structure whose $n(n+1)/2$ entries can be constructed from only $2n$ values of $L_k^{(j)}$ and $L_k^{(i)}$ for $k = 1, 2, \dots, n$.

The integrand of the definition of $L_k^{(j)}$ has the degree higher by one than the integrand of the original definition of V_{ij} , therefore to keep accuracy of the values of $L_k^{(j)}$, it seems that the quadrature formula of slightly higher accuracy have to be used. However, what finally to be calculated are the values of V_{ij} , so $L_k^{(j)}$ may be calculated by some quadrature formula that is just sufficient to integrate V_{ij} by the original formula. The errors of $L_k^{(j)}$ which are introduced by this reduced integration will be canceled when V_{ij} is calculated from $L_k^{(j)}$.

FEM Matrix of Laplacian

In our situation (without curved coordinate transformation), the FEM matrix of Laplacian depends only on basis functions selected. Therefore, when the region of analysis is divided into FEs, and each local coordinate inside the FE is transformed linearly to the standard interval $[-1, 1]$, then those FEs whose set of LBPs are the same

have the same matrix of discretized Laplacian except the scaling factors. Therefore, when we use LBPs whose abscissas are for example G-L type, if the types of basis functions of the FEs are not so many, we can reduce the amount of storage by keep FEM matrices of the Laplacian for the standard interval correspondingly, and use them selectively with proper scaling depending on the size of the FE.

We can reduce the amount of storage for those FE whose order of basis function n is large. The matrix elements of the Laplacian of 1-D are written as:

$$K_{ij}^{(j)} = \int_I \frac{d}{dx} \left(\frac{d}{dx} v_i^{(j)}(x) \right) \frac{d}{dx} v_j^{(j)}(x) dx = \int_I \frac{d}{dx} \left(\frac{P^{(j)}(x)}{x - \alpha_i} \right) \cdot \frac{d}{dx} \left(\frac{P^{(j)}(x)}{x - \alpha_j} \right) dx.$$

Then we have:

$$K_{ij}^{(j)} = \begin{cases} \frac{1}{\alpha_i - \alpha_j} (A^{(j)} - A^{(j)}) + \frac{1}{(\alpha_i - \alpha_j)^2} (A^{(j)2} + A^{(j)2}) & (i \neq j), \\ 0 & (i = j), \end{cases}$$

Therefore, to calculate the vector w which is a matrix-vector multiplication of the matrix $K^{(j)}$ and the vector u , we need not store $C_{ij}^{(j)}$ and calculate:

$$K_{ij}^{(j)} u_j = \begin{cases} \frac{1}{\alpha_i - \alpha_j} (A^{(j)} - A^{(j)}) u_j - \sum_j \frac{C_{ij}^{(j)2}}{(\alpha_i - \alpha_j)^2} (A^{(j)2} u_j) & (i \neq j), \\ 0 & (i = j). \end{cases}$$

Here, we have defined:

$$A^{(j)} \equiv \int_I \frac{d}{dx} v_i^{(j)}(x) \cdot \frac{d}{dx} v_j^{(j)}(x) dx, \\ A^{(j)2} \equiv \int_I \left(\frac{d}{dx} v_i^{(j)}(x) \right)^2 dx, \\ A^{(j)3} \equiv -2 \int_I \left(\frac{d}{dx} v_i^{(j)}(x) \right) \left(\frac{d}{dx} v_j^{(j)}(x) \right)^2 dx, \\ B_k \equiv \int_I \frac{d}{dx} v_k^{(j)}(x) \cdot \frac{d}{dx} v_j^{(j)}(x) dx.$$

If we set auxiliary values:

$$\left\{ \begin{aligned} \beta_j^{(j)} &\equiv \sum_j A^{(j)} u_j, \quad \alpha_j^{(j)} \equiv \sum_j C_{ij}^{(j)2} u_j, \\ \beta_j^{(j)2} &\equiv A^{(j)2} u_j, \quad \alpha_j^{(j)2} \equiv \sum_j C_{ij}^{(j)2} u_j, \\ \beta_j^{(j)3} &\equiv A^{(j)3} u_j, \quad \alpha_j^{(j)3} \equiv \sum_j C_{ij}^{(j)2} u_j, \end{aligned} \right.$$

and calculate the vector w efficiently:

$$w_i = \sum_j \left\{ -\frac{C_{ij}^{(j)2}}{(\alpha_i - \alpha_j)^2} \beta_j^{(j)2} + \frac{C_{ij}^{(j)2}}{(\alpha_i - \alpha_j)^2} \beta_j^{(j)3} - C_{ij}^{(j)2} \beta_j^{(j)3} \right\} + B_{ij} u_j.$$

Therefore, $n(n+1)/2$ elements of the symmetric matrix of discretized Laplacian $K_{ij}^{(j)}$ can be built

from six values of $A_k^{(j)}$, $A_k^{(j)2}$, $A_k^{(j)3}$ and B_k for $k = 1, \dots, n$.

If we define the anti-symmetric matrix $C_{ij}^{(j)}$ as:

$$C_{ij}^{(j)} = \begin{cases} \frac{1}{\alpha_i - \alpha_j} & (i \neq j), \\ 0 & (i = j), \end{cases}$$

Then we have:

$$K_{ij}^{(j)} = (C_{ij}^{(j)})^2 (A^{(j)} - A^{(j)}) + (C_{ij}^{(j)2})^2 (A^{(j)2} + A^{(j)2}) + (C_{ij}^{(j)2})^2 (A^{(j)3} - A^{(j)3}) + \alpha_k B_k.$$

Therefore, to calculate the vector w which is a matrix-vector multiplication of the matrix $K^{(j)}$ and the vector u , we need not store $C_{ij}^{(j)}$ and calculate:

$$K_{ij}^{(j)} u_j = \begin{cases} \frac{1}{\alpha_i - \alpha_j} (A^{(j)} - A^{(j)}) u_j + \frac{1}{(\alpha_i - \alpha_j)^2} (A^{(j)2} + A^{(j)2}) u_j & (i \neq j), \\ 0 & (i = j). \end{cases}$$

Here, we have defined:

$$A^{(j)} \equiv \int_I \frac{d}{dx} v_i^{(j)}(x) \cdot \frac{d}{dx} v_j^{(j)}(x) dx, \\ A^{(j)2} \equiv \int_I \left(\frac{d}{dx} v_i^{(j)}(x) \right)^2 dx, \\ A^{(j)3} \equiv -2 \int_I \left(\frac{d}{dx} v_i^{(j)}(x) \right) \left(\frac{d}{dx} v_j^{(j)}(x) \right)^2 dx, \\ B_k \equiv \int_I \frac{d}{dx} v_k^{(j)}(x) \cdot \frac{d}{dx} v_j^{(j)}(x) dx.$$

If we set auxiliary values:

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and calculate the vector w efficiently:

$$w_i = \sum_j \left\{ -\frac{C_{ij}^{(j)2}}{(\alpha_i - \alpha_j)^2} \beta_j^{(j)2} + \frac{C_{ij}^{(j)2}}{(\alpha_i - \alpha_j)^2} \beta_j^{(j)3} - C_{ij}^{(j)2} \beta_j^{(j)3} \right\} + B_{ij} u_j.$$

For this case of 1-D, by this method the number of arithmetic operations is $O(n^2)$, therefore it has the same complexity to matrix-vector multiplication of formed matrix $K^{(j)}$ and the vector u . However, if n is very large, this method does not store nor hold the matrix $K^{(j)}$ explicitly, therefore the amount of storage requirement to make the calculation is as long as the matrix $C_{ij}^{(j)}$ is not formed nor stored.

3.2 Case of 2-Dimension

Tensorial Product Base Functions

When the local FEM element is parameterized by a direct product of the local coordinates, the basis functions are taken as tensor products of LBPs in each coordinate axis.

where

$$v_{i_1, i_2}^{(j)}(x, y) = \frac{P^{(j)}(x)}{x - \alpha_{i_1}} \frac{P^{(j)}(y)}{y - \beta_{i_2}} \equiv \prod_{k=1}^n (x - \alpha_k) \prod_{l=1}^n (y - \beta_l).$$

Then matrix elements of the potential can be written by combinations of values of entries of LBPs in each coordinate axis:

$$V_{ij} = V_{(i_1, i_2), (j_1, j_2)} = \int \int_{\Omega} \frac{P^{(j)}(x)}{x - \alpha_{i_1}} \frac{P^{(j)}(y)}{y - \beta_{i_2}} U(x, y) \frac{P^{(j)}(x)}{x - \alpha_{j_1}} \frac{P^{(j)}(y)}{y - \beta_{j_2}} dx dy.$$

Matrix elements of 2-D potential $U(x, y)$ are:

$$V_{ij} = \int \int_{\Omega} \frac{P^{(j)}(x)}{x - \alpha_{i_1}} \frac{P^{(j)}(y)}{y - \beta_{i_2}} U(x, y) \frac{P^{(j)}(x)}{x - \alpha_{j_1}} \frac{P^{(j)}(y)}{y - \beta_{j_2}} dx dy.$$

here $e_1 = 0$ or 1 and $e_2 = 0$ or 1.

The matrix elements of the potential can be written by combinations of values of entries of LBPs in each coordinate axis:

$$V_{(i_1, i_2), (j_1, j_2)} = \frac{1}{(\alpha_{i_1} - \alpha_{j_1})(\beta_{i_2} - \beta_{j_2})} (L_{i_1, j_1}^{(j)} - L_{i_1, j_1}^{(j)} - L_{i_1, j_1}^{(j)} + L_{i_1, j_1}^{(j)}).$$

if $i_1 \neq j_1, i_2 \neq j_2$,

$$\frac{1}{\beta_{i_2} - \beta_{j_2}} \left(\frac{L_{i_1, j_1}^{(j)} - L_{i_1, j_1}^{(j)}}{\alpha_{i_1} - \alpha_{j_1}} \right), \quad \text{if } i_1 = j_1, i_2 \neq j_2,$$

$$\frac{1}{\alpha_{i_1} - \alpha_{j_1}} \left(\frac{L_{i_1, j_1}^{(j)} - L_{i_1, j_1}^{(j)}}{\beta_{i_2} - \beta_{j_2}} \right), \quad \text{if } i_1 \neq j_1, i_2 = j_2 = q,$$

$$L_{i_1, j_1}^{(j)}, \quad \text{if } i_1 = j_1 = p, i_2 = j_2 = q.$$

Therefore, by the above algebraic relations, all $n^2(n^2 + 1)/2$ entries of the symmetric matrix $V_{(i_1, i_2), (j_1, j_2)}$ can be built from only $4n^2$ values of $L_{i_1, j_1}^{(j)}$. The storage requirement can be reduced if this knowledge on the structure of the matrix elements is used.

The algebraic structure of this matrix elements is derived from only the simple identity of the fractions and the use of the LBPs.

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correspond to the types of basis functions inside elements but not so much amount of storage requirement, and use the stored 1-D matrices selectively with proper scalings.

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3.3 Case of 3-Dimension

Tensorial Product Base Functions

Similar to the 2-D case, tensorial products of LBPs in each local coordinate are taken as basis functions:

$$v_{i_1, i_2, i_3}^{(j)}(x, y, z) = \frac{P^{(j)}(x)}{x - \alpha_{i_1}} \frac{P^{(j)}(y)}{y - \beta_{i_2}} \frac{P^{(j)}(z)}{z - \gamma_{i_3}} \equiv \prod_{k=1}^n (x - \alpha_k) \prod_{l=1}^n (y - \beta_l) \prod_{m=1}^n (z - \gamma_m).$$

Then matrix elements of the potential can be written by combinations of values of entries of LBPs in each coordinate axis:

$$V_{ij} = V_{(i_1, i_2, i_3), (j_1, j_2, j_3)} = \int \int \int_{\Omega} \frac{P^{(j)}(x)}{x - \alpha_{i_1}} \frac{P^{(j)}(y)}{y - \beta_{i_2}} \frac{P^{(j)}(z)}{z - \gamma_{i_3}} U(x, y, z) \frac{P^{(j)}(x)}{x - \alpha_{j_1}} \frac{P^{(j)}(y)}{y - \beta_{j_2}} \frac{P^{(j)}(z)}{z - \gamma_{j_3}} dx dy dz.$$

Matrix elements of 3-D potential $U(x, y, z)$ are:

$$V_{ij} = \int \int \int_{\Omega} \frac{P^{(j)}(x)}{x - \alpha_{i_1}} \frac{P^{(j)}(y)}{y - \beta_{i_2}} \frac{P^{(j)}(z)}{z - \gamma_{i_3}} U(x, y, z) \frac{P^{(j)}(x)}{x - \alpha_{j_1}} \frac{P^{(j)}(y)}{y - \beta_{j_2}} \frac{P^{(j)}(z)}{z - \gamma_{j_3}} dx dy dz.$$

here $e_1 = 0$ or 1 and $e_2 = 0$ or 1 and $e_3 = 0$ or 1.

The matrix elements of the potential can be written by combinations of values of entries of LBPs in each coordinate axis:

$$V_{(i_1, i_2, i_3), (j_1, j_2, j_3)} = \frac{1}{(\alpha_{i_1} - \alpha_{j_1})(\beta_{i_2} - \beta_{j_2})(\gamma_{i_3} - \gamma_{j_3})} (L_{i_1, j_1, i_2, j_2, i_3, j_3}^{(j)} - L_{i_1, j_1, i_2, j_2, i_3, j_3}^{(j)} - L_{i_1, j_1, i_2, j_2, i_3, j_3}^{(j)} + L_{i_1, j_1, i_2, j_2, i_3, j_3}^{(j)}).$$

if $i_1 \neq j_1, i_2 \neq j_2, i_3 \neq j_3$,

$$\frac{1}{(\beta_{i_2} - \beta_{j_2})(\gamma_{i_3} - \gamma_{j_3})} \left(\frac{L_{i_1, j_1, i_2, j_2, i_3, j_3}^{(j)} - L_{i_1, j_1, i_2, j_2, i_3, j_3}^{(j)}}{\alpha_{i_1} - \alpha_{j_1}} \right), \quad \text{if } i_1 = j_1, i_2 \neq j_2, i_3 \neq j_3,$$

$$\frac{1}{(\alpha_{i_1} - \alpha_{j_1})(\gamma_{i_3} - \gamma_{j_3})} \left(\frac{L_{i_1, j_1, i_2, j_2, i_3, j_3}^{(j)} - L_{i_1, j_1, i_2, j_2, i_3, j_3}^{(j)}}{\beta_{i_2} - \$$