

An Optimization Technology of Software Auto-Tuning Applied to Machine Learning Software

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Introduction

This poster shows to enhance the performance of an application program by software auto-tuning (AT). Performance factors of a target program are formed into performance parameters. So that to enhance performance is said that to estimate an appropriate combination of performance parameters. The estimation while executing a target program should be designed, to set a combination before each execution and evaluate the performance after each execution. For the estimation, we develop a simple AT tool “DSICE”. The estimation by DSICE is based on the method of iterative collinear exploration using d-Spline [1][2]. The estimation method is built in the AT infrastructure ppOpen-AT [3]. DSICE makes the estimation method to be used in a more general form. Then we apply DSICE to estimating hyperparameters’ configuration of a machine learning model.

The AT Tool “DSICE”

DSICE : D-Spline within Iterative Collinear Exploration

➤ DSICE as a function embedded into a target program

➤ Input

- Combinational patterns of performance parameters
- A single metric value (the lower the better) to evaluate the performance

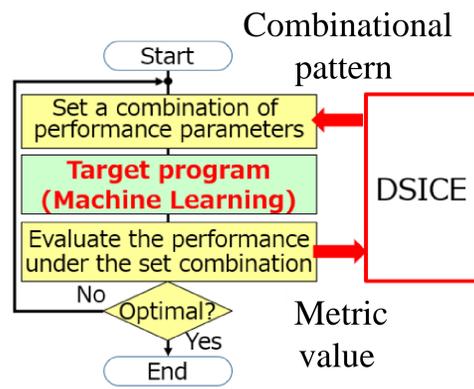


Fig.1 Procedure of DSICE: that iterates determining a combinational pattern of performance parameters among the input patterns, and sampling a metric value under the set combination, until an acceptable combination is found.

➤ Output

- An optimum combination under the input metric among the input patterns

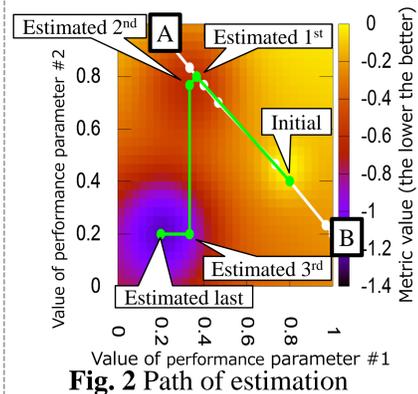


Fig. 2 Path of estimation

- Algorithm to estimate an optimum combination of performance parameters
 1. Directional exploration (Fig.3)
 2. Collinear exploration (Fig.4)
 3. Iterating 1. and 2. until convergence

- ✓ A darker point as a better combination
- ✓ A white line as a range of collinear exploration on Fig.4
- ✓ White points as the sampled combination on white line
- ✓ Green points as the estimated optimum combination
- ✓ Green lines as the path of estimated optimum points

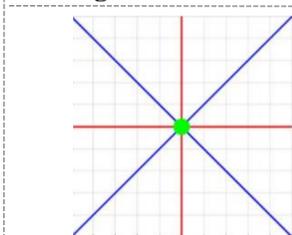


Fig.3 Determining a line[1]:

- ✓ A red line as a variable performance parameter
- ✓ A blue line as variable performance parameters

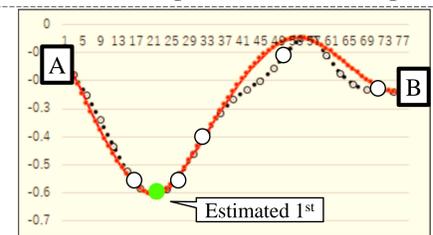


Fig.4 Fitting by d-Spline following some sampled metric value:

- Estimating the minimum metric value from A to B on Fig.2 [2].
- ✓ White points as each sampled value of combinations
- ✓ A red line as one-dimensional d-Spline following white points
- ✓ A green point as the value of the estimated 1st combination

The Application to Machine Learning

Estimating hyperparameters’ configuration of a CNN model for an object classification problem called CIFAR10 reported in [4].

- Learning model : CNN
- Total patterns : 164,025
- ◆ Metric value as Z considering both of classification accuracy and learning time

Table 1: Hyperparameters of CNN

	Parameters	Patterns
1 st layer	Filters	5
	Output channels	9
2 nd layer	Filters	5
	Output channels	9
3 rd layer	Neurons	9
4 th layer	Neurons	9

- ◆ $Z = (a \times L) + (b \times T)$
- ◆ L as accuracy loss
- ◆ T as normalized learning time
- ◆ a as weight for L
- ◆ b as weight for T
- ✓ $a=1.0$, $b=0.5$ in this experiment

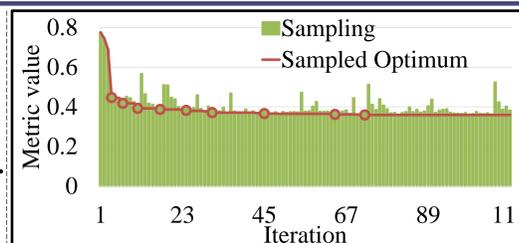


Fig.5: Transition of metric value estimated by DSICE

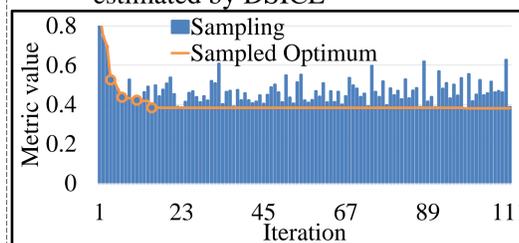


Fig.6: Transition of metric value estimated by Random Search

The estimated metric value are shown on Fig.5 by DSICE and on Fig.6 by Random Search. DSICE converges in 111 iterations for total 164,025 patterns. The accumulation of metric value is about 45 (green area) for DSICE, and about 50 (blue area) for Random Search. Thus DSICE reduces about 10% from the accumulation of metric value.

Conclusion

We develop a simple AT tool “DSICE” to estimate a combination of performance parameters for a target program, and apply DSICE to estimating hyperparameters’ configuration of a CNN model. DSICE converges efficiently within approximately 100 iterations for 164,025 configuration patterns, and reduces 10% from the accumulation of metric value during estimation. We will apply DSICE to other performance optimization problems in our future work.

Acknowledgments

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Reference

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